

# MERU UNIVERSITY OF SCIENCE AND TECHNOLOGY

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## University Examinations 2019/2020

SECOND THIRD SECOND SEMESTER EXAMINATION FOR THE DEGREE OF  
BACHELOR OF TECHNOLOGY IN ELECTRICAL AND ELECTRONIC ENGINEERING

### EET 3370: DIGITAL SIGNAL PROCESSING

DATE: APRIL 2020

TIME: 2 HOURS

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INSTRUCTIONS: Answer question *one* and any other *two* questions

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#### QUESTION ONE (30 MARKS)

- a). Define the following terms:
- i). Aliasing (2 marks)
  - ii). Nyquist sampling frequency (2 marks)
- b). Explain in the summary the process of analogue to digital conversion (6 marks)
- c). Draw a basic digital filter that can be used as a three-sample averager, naming all its components (5 marks)
- d). Find the unit-sample response of a digital filter whose output is given as  
 $y(n) = 1/3(x(n+1) + x(n) + x(n-1))$  (6 marks)
- e). A first order recursive filter whose input is  $x(n)$  has an output given as  $y(n) = ay(n-1) + x(n)$  where  $a$  is a constant. Determine whether the filter is stable or not. (4 marks)
- f). Find the Discrete Fourier Transform (DFT) of a digital system whose unit impulse response is defined by  $h(n) = \begin{cases} \frac{1}{3} & \text{for } 0 \leq n \leq 2 \\ 0 & \text{otherwise} \end{cases}$  (5 marks)
- g). Find the z – transform of a filter whose impulse response is given as  $h(n) = \begin{cases} a^n & \text{for } n \leq 0 \\ 0 & \text{otherwise} \end{cases}$  (4 marks)

#### QUESTION TWO (15 MARKS)

- a). Explain any two properties of the DFT. (4 marks)
- b). Find the circular convolution for  $x(n) = \begin{cases} 1 & \text{for } n = 0 \\ 0.5 & \text{for } n = 1 \\ 0 & \text{otherwise} \end{cases}$  and  $h(n) = \begin{cases} 0.5 & \text{for } n = 0 \\ 1 & \text{for } n = 1 \\ 0 & \text{otherwise} \end{cases}$  (5 marks)

- c). Derive analytically, the decimation in time FFT algorithm. (6 marks)

**QUESTION THREE (15 MARKS)**

- a). Find the z – transform of the second order recursive filter given by

$$h(n) = \begin{cases} r^n \cos(\omega_0 n) & \text{for } n \geq 0 \\ 0 & \text{otherwise} \end{cases} \quad (6 \text{ marks})$$

- b). Determine the system function for a system whose output is given as

$$y(n) = a_1 y(n-1) + a_2 y(n-2) + b_0 x(n) + b_1 x(n-1) \quad (4$$

marks)

- c). State the four types of singularities generated by elementary filters with respect to the complex z – plane. (4 marks)

**QUESTION FOUR (15 MARKS)**

- a). Perform Direct Form II implementation for a filter given by

$$y(n) = 2r \cos(\omega_0) y(n-1) - r^2 y(n-2) + x(n) - r \cos(\omega_0) x(n-1) \quad (9 \text{ marks})$$

- b). Explain the difference between recursive and causal filters (4 marks)

- c). What is meant by FIR and IIR (2 marks)

**QUESTION FIVE (15 MARKS)**

- a). Explain the performance differences between FIR and IIR filters. (6 marks)

- b). Design an FIR filter using the DFT / windowing procedure. The filter is specified as:

$$\text{passband: } -1 \leq |H(e^{j\omega})|_{\text{dB}} \leq 0 \quad \text{for } 0.42\pi \leq \omega \leq 0.61\pi$$

$$\text{stopband: } |H(e^{j\omega})|_{\text{dB}} < -60 \quad \text{for } 0 \leq \omega \leq 0.16\pi \text{ and } 0.87\pi \leq \omega \leq \pi$$

(9 marks)